

## Chapter 6. Problems

*"All programming problems should include design pseudo code either as a separate design document or embedded comments in the code."*

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1S. Write an assembly code equivalent for the following C code segment:

```
int i;           //int is 2 bytes
i=0;
while (i < 35){
    i = i+2;
}
```

Solution

```
i0 equ 0x80          // least significant byte of integer i
i1 equ 0x81          // most significant byte of integer i

CLRF    i0
CLRF    i1
MOVLW   35

w_loop: CPFSLT i0
        BRA     done
        BRA     cont

cont:   INCF    i0
        INCF    i0
        BRA     w_loop

done   ; continue with the rest of the program
```

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1U. Write an assembly code equivalent for the following C code segment:

```
int i;    // int is 2 bytes
i=200;
while (i < 126){
    i = i-4;
}
```

Solution

---

2S. Write an assembly code equivalent for the following C code segment:

```
int i;           //int is 2 bytes
for (i=5; i≤29; i++)
    i = i+3;
```

Solution

```
i0 equ 0x80          // least significant byte of integer i
i1 equ 0x81          // most significant byte of integer i

MOVLW   5
MOVWF   i0
```

```

CLRF    i1
MOVLW   29
f_loop: CPFSGT i0
         BRA    cont
         BRA    done
cont:   INCF    i0
         INCF    i0
         INCF    i0
         INCF    i0
         BRA    f_loop
done    ; continue with the rest of the program

```

2U. Write an assembly code equivalent for the following C code segment:

```

int i;           //int is 2 bytes
for (i=15; i≤129; i=i+2)
    i = i+6;

```

Solution

3S. Rewrite the following C code in assembly code and show the location of each variable in memory:

```

float fnum;
fnum = 200.625;

```

Solution

```

fnum    equ 0x80      ; 4 bytes
        ; convert 200.625 to single precision float → 11001000.101 → 1.1001000101x27
        ; 0100 0011 0100 1000 1010 0000 0000 0000
        ; Use indirect addressing to move the 4 bytes into to fnum
LFSR    FSR0,0x80      ; Set the base
MOVLW   0x00
MOVWF   POSTINC0
MOVLW   0xA0
MOVWF   POSTINC0
MOVLW   0x48
MOVWF   POSTINC0
MOVLW   0x43
MOVWF   POSTINC0

```

3U. Rewrite the following C code in assembly code and show the location of each variable in memory:

```

float fnum;
fnum = 1280.625;

```

Solution

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4S. Rewrite the following C code in assembly code and show the location of each variable in memory:

```
int id;
char grade;
float f_a[3];
struct student{
    unsigned char name[40];
    int grade;
} class [35];

class[3].grade = 100;
```

Solution

```
id      equ 0x80      ; 2 bytes
grade   equ 0x82      ; 1 byte
f_a    equ 0x83      ; 4 bytes each, 3 elements
class   equ 0x8F      ; 40 + 2 bytes each, 35 elements

        MOVWL .100          // dot before the number indicated decimal
        MOVWF 0x135
        CLRF  0x136
```

---

4U. Rewrite the following C code in assembly code and show the location of each variable in memory:

```
int id;
float f_a[5];
char grade;
struct student{
    unsigned char name[20];
    int grade;
} class [15];

class[4].grade = 20;
```

Solution

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5S. Write an assembly code segment using indirect addressing to implements the following C code segment:

```
char name1 [32], name2[32];
char equ_flag;
if (strcmp (name1, name2)
    equ_flag = 0;
else
    equ_flag = 1;
```

Solution

```
name1     equ 0x80      ; 32 bytes
name2     equ 0xA0      ; 32 bytes
equ_flag  equ 0xC0      ; 1 byte
i         equ 0xC1      ; 1byte

        LFSR    FSR0, name1 ; set base
        LFSR    FSR1, name2
        CLRF    i
```

	CLRF	equ_flg
cmp:	MOVF	POSTINC0, 0
	CPFSEQ	POSTINC1
	BRA	done ; not equal
	INCF	i
	MOVLW	.31
	CPFSGT	i
	BRA	cmp ; continue comparing
	INCF	equ_flg ; strings are equal
done:		

5U. Write an assembly code segment using indirect addressing to implements the following C code segment:

```
char apt1 [24], apt2[24];
char next;
if (strcmp (apt1, apt2))
    next = 0;
else
    next = 1;
```

Solution

6S. Write an assembly code segment using indirect addressing to implements the following C code segment:

```
char source[48], dest[48];
char I;

for (i=0; i<48 ; i++){
    dest[i] = source[i];
}
```

Solution

source	equ	0x80 ; 48 bytes
dest	equ	0xB0 ; 48 bytes
i	equ	0xE0 ; 1 byte
	LFSR	FSR0, source ; set base
	LFSR	FSR1, dest
	CLRF	i
xfer:	MOVFF	POSTINC0, POSTINC1
	INCF	i
	MOVLW	.47
	CPFSGT	i
	BRA	xfer

6U. Write an assembly code segment using indirect addressing to implements the following C code segment:

```
char source[43], exch[43], temp;
int i;
```

```

i=0;
while (i<43){
    temp = exch[i];
    exch[i] = source[42 - i];
    source[42-i] = temp;
    i++;
}

```

### Solution

7S. Using MPLAB and the following sample Bubble Sort C code, write equivalent PICmicro assembly code using indirect addressing.

```

void Bsort( int data[20] )
{
    int temp, i, swapped;
    swapped = 1;
    while (swapped == 1){
        swapped = 0;
        for (i=0; i<20 ; i++){
            if (data[i] > data[i+1]){
                temp = data[i];
                data[i]= data[i+1];
                data[i+1]=temp;
                swapped = 1;
            } // if()
        } // for()
    } // while()
} //Bsort()

```

### Solution

Loop2: LFSR        0, 0x90                      ; prep with first address LFSR        1, 0x91                      ; prep with the address after the first MOVF        INDF0, W                      ; copy value at FSR0 to WREG CPFSGT     INDF1                          ; compare WREG with FSR1 BRA         NGT1                          ; if !( (FSR0) > (FSR1) ) ;swap the value of FSR0 is already cached in WREG MOVFF      INDF1, INDF0 ; move FSR1 to FSR0 MOVWF      INDF1                          ;move prev value of FSR0 into FSR1 MOVF       POSTINC0                      ; temp increment addr of FSR0 ; time to reset the FSR1 address... ; FSR0 only moves when FSR1 reaches the end and is never reset backwards MOVFF      FSR0L, FSR1L                ; copy address of FSR0 to FSR1 MOVFF      FSR0H, FSR1H                ; MOVF       POSTDEC0                      ; decrement FSR0 back to it's proper value BRA Loop2 NGT1: MOVF       POSTINC1                      ; increment FSR1 ; this is a specialized piece, for a general case we have to load in the end value ; and compare the low and high bytes MOVLW      0x95                          ; move the end address into WREG CPFSEQ     FSR1L                        ;compare with the ONLY the low byte BRA        Loop2                        ; not equal..continue ;is equal.. increment FSR0 and reset FSR1 to FSR0+1 MOVF       POSTINC0                      ; increment FSR0 MOVF       POSTINC0                      ; increment FSR0 (temp)
--

```

MOVFF    FSR0L, FSR1L      ; copy low-byte
MOVFF    FSR0H, FSR1H      ; copy high-byte
MOVF     POSTDEC0         ; decrement back to proper address
MOVLW    0x94              ; end address - 1
CPFSEQ   FSR0L            ;compare
BRA     Loop2              ; not equal .. continue
; all done and the 'array' is sorted largest to smallest

```

7U. Using MPLAB and the following sample Binary Search C code, write equivalent PICmicro assembly code using indirect addressing.

```

/* Search for key in array A and return the location of key:
 * A[] is a sorted array of elements
 * imin and imax are limits of search range.
 */
int binary_search(int A[], int key, int imin, int imax)
{
    // test if array is empty
    if (imax < imin)
        // set is empty, so return value showing not found
        return (-1); // search failed to find the key
    else
    {
        // calculate midpoint to cut set in half
        int imid = midpoint(imin, imax);

        // three-way comparison
        if (A[imid] > key)
            // key is in lower subset
            return binary_search(A, key, imin, imid-1);
        else if (A[imid] < key)
            // key is in upper subset
            return binary_search(A, key, imid+1, imax);
        else
            // key has been found
            return imid;
    }
}

```

### Solution

8U. Write a C program that includes a function call, if statement, indirect addressing and a loop. Upon compilation, analyze the .lst file. The analysis should clearly relate the C statements and variables to their equivalent and location in the assembly code. Also, determine the final value assigned to every variable after the program execution.

### Solution